

Lightweight Materials Their Properties, Technologies and Advanced Applicability

1.2 Material oriented approaches

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Lightweight Materials - Their Properties, Technologies and Advanced Applicability

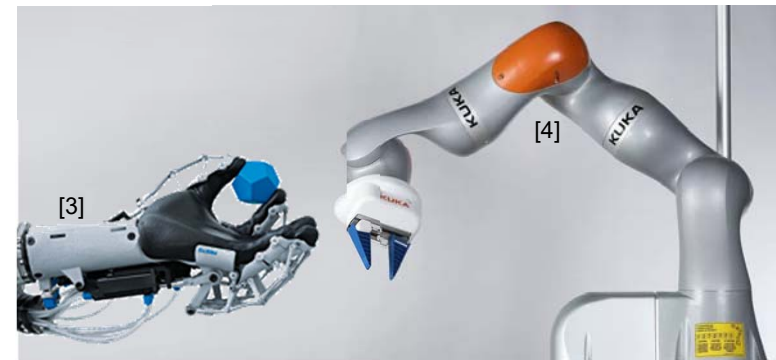
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	1	1.3 Metallic Materials Mechanisms of Strength Increase and their Industrial Use
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Lightweight design

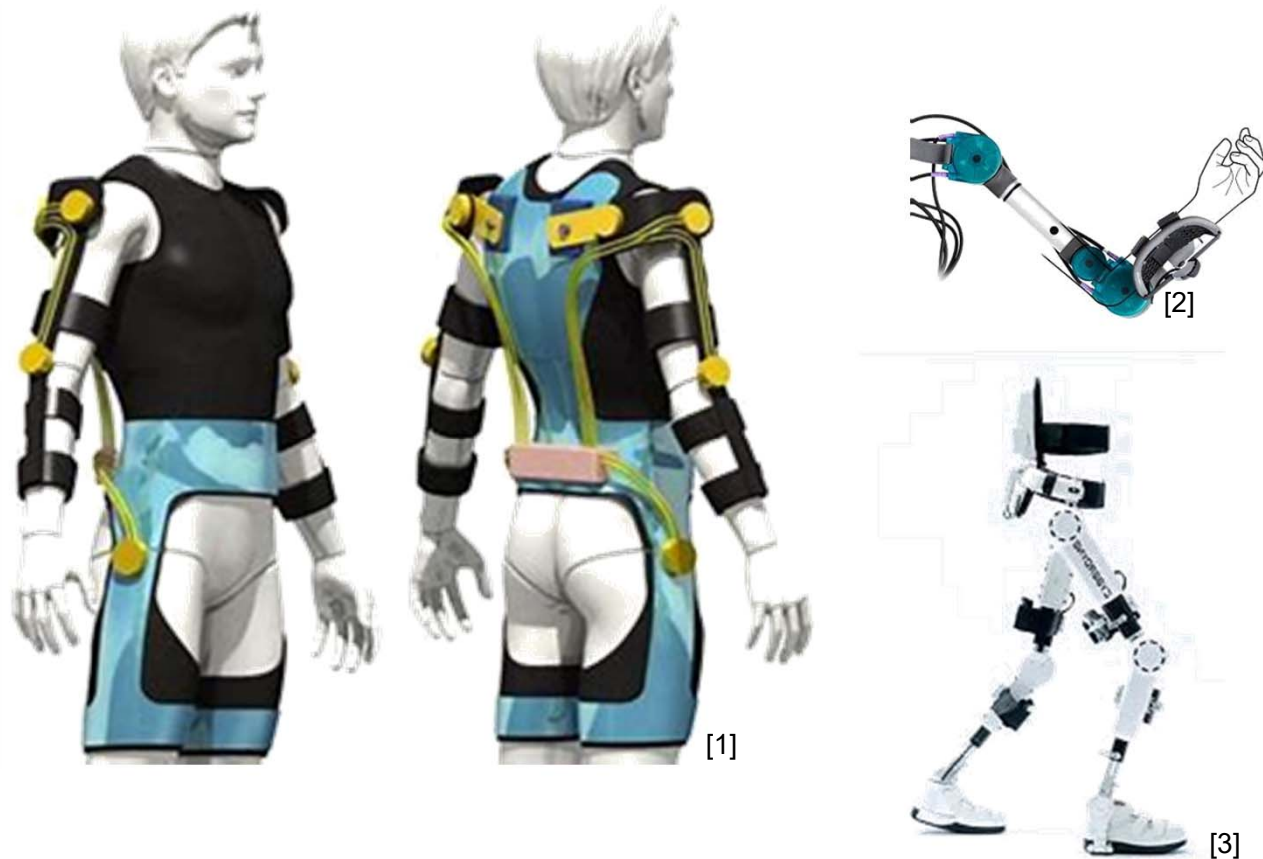
How can we find a component's right material?



1.2 Material oriented approaches

Lightweight design

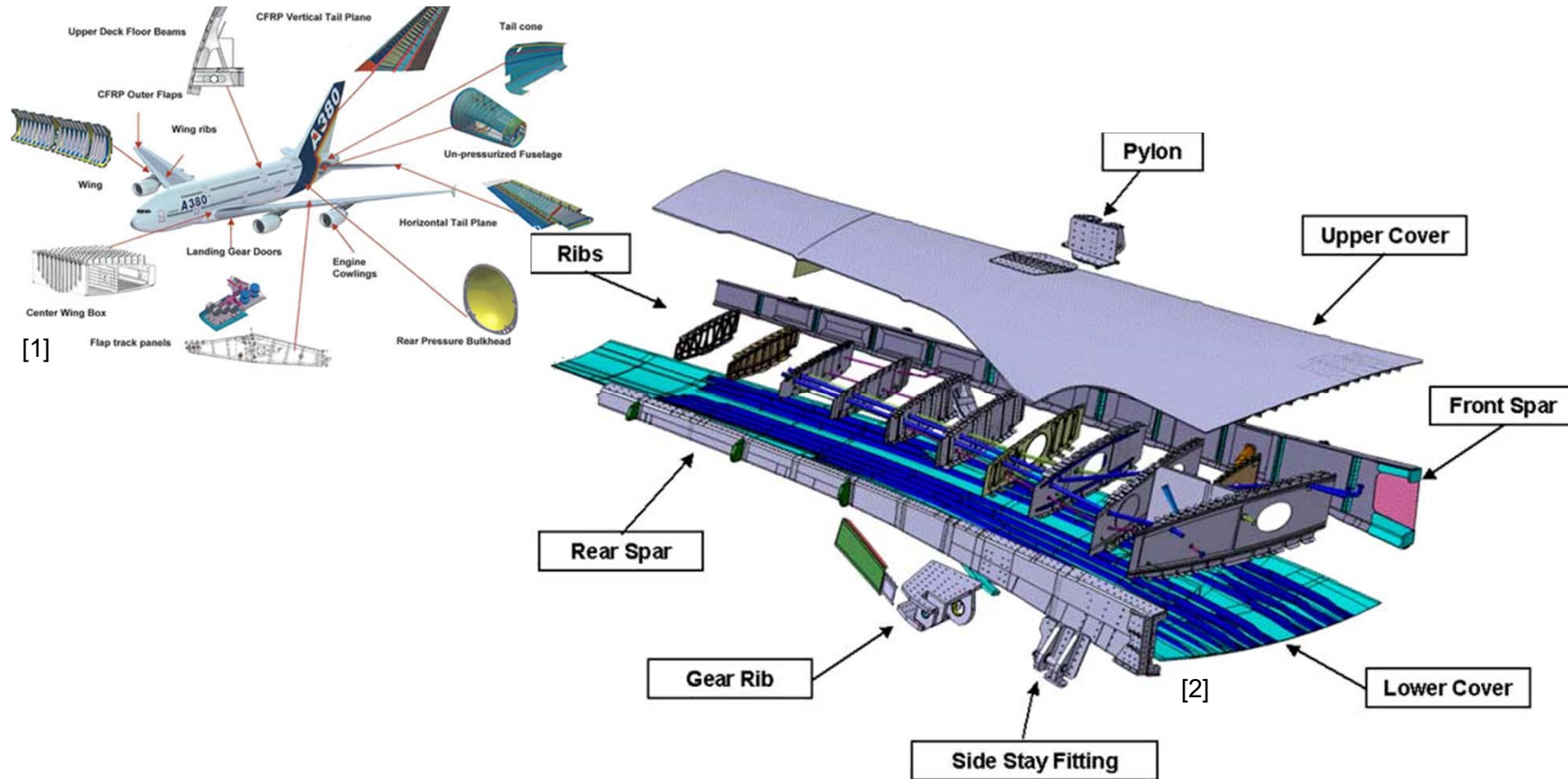
How can we find a component's right material?



1.2 Material oriented approaches

Lightweight design

How can we find a component's right material?

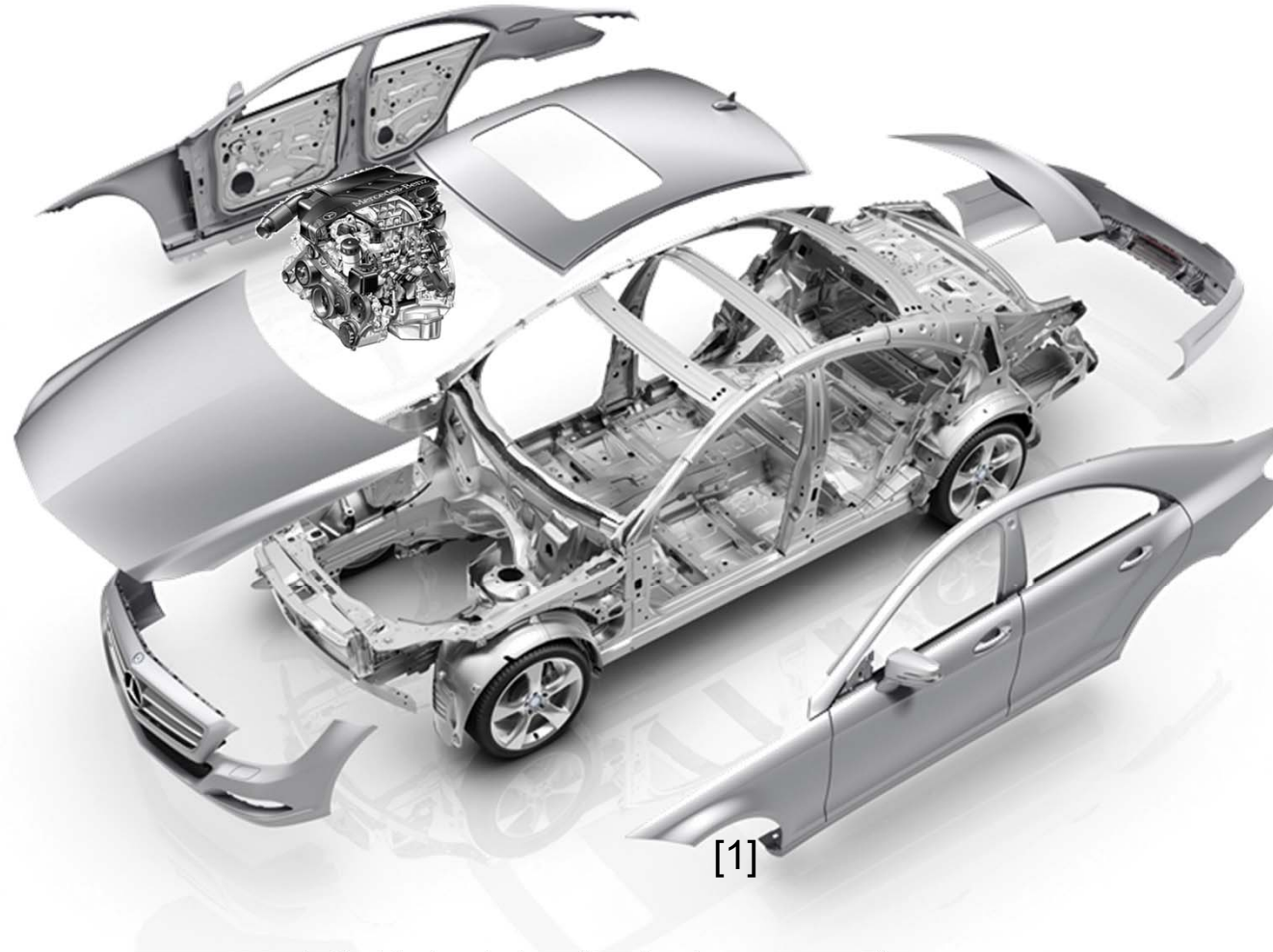


(Source: Airbus,)

1.2 Material oriented approaches

Lightweight design

How can we find a component's right material?

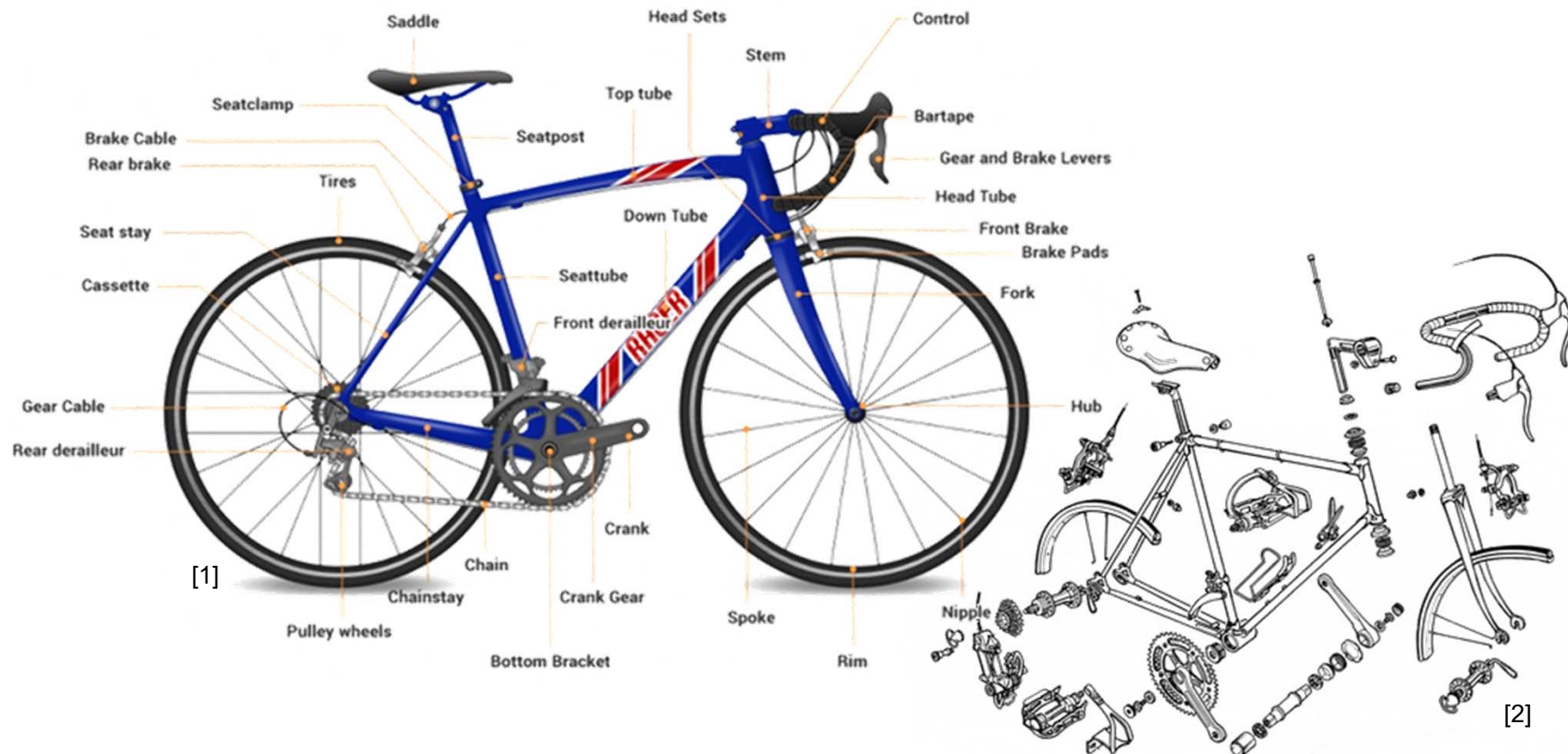


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1.2 Material oriented approaches

Lightweight design

How can we find a component's right material?



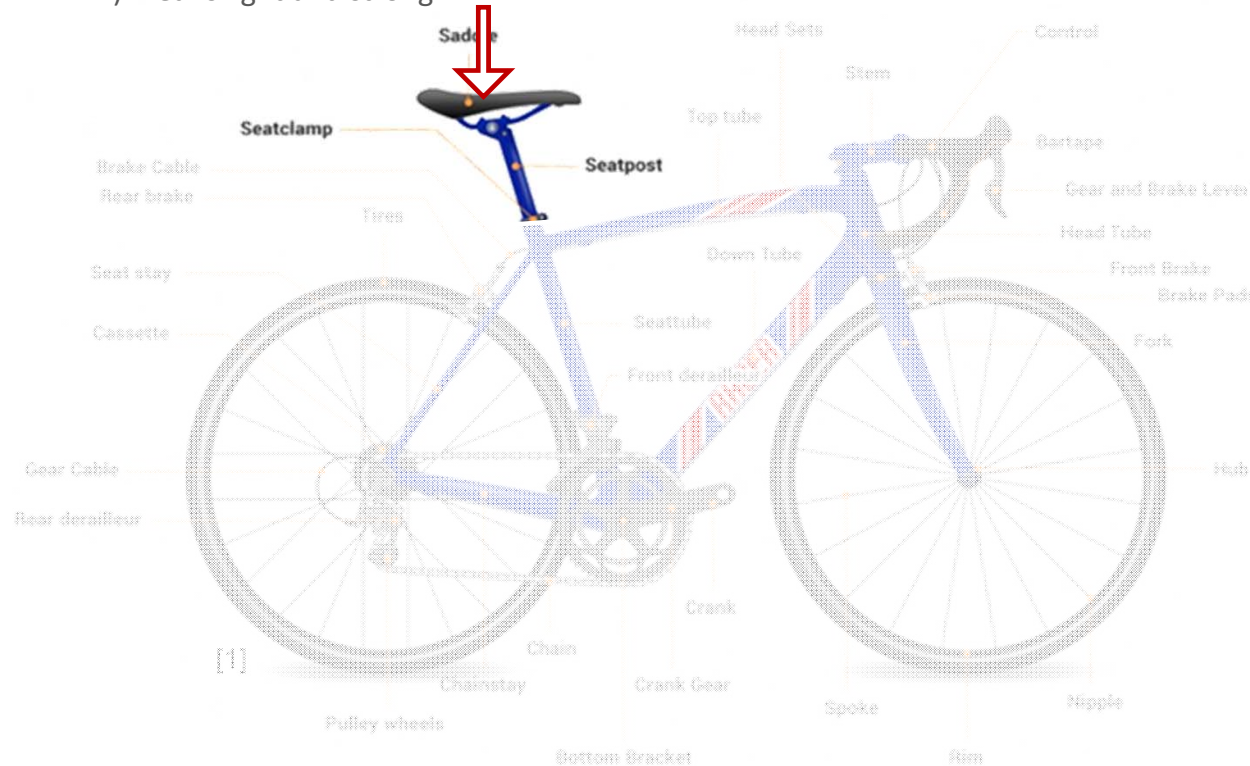
*) means light and strong

1.2 Material oriented approaches

Design and dimensioning

How can we find the seat post's right* material?

*) means light and strong



Given:

- Cyclist's weight $m=100$ kg
- Horizontal distance between saddle and seat clamp $x=100$ mm
- Vertical distance between saddle and seat clamp $y=200$ mm
- Diameter of the seat post $D=10$ mm

Wanted:

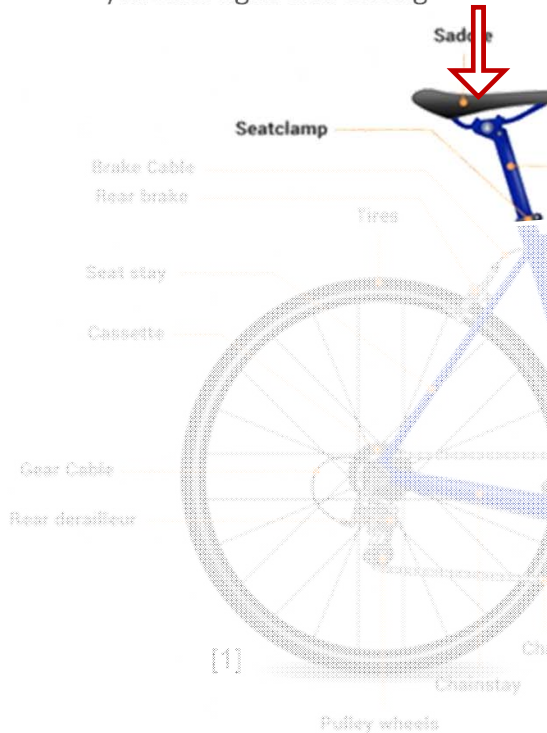
- Location of the highest load
- Type of local load
- Level of local load
- The seat post's right material choice (i.e. the lightest considered metal)

1.2 Material oriented approaches

Design and dimensioning

How can we find the seat post's right* material?

*) means light and strong



$m = 100 \text{ kg}$
 $x = 100 \text{ mm}$
 $y = 200 \text{ mm}$
 $D = 10 \text{ mm}$

$1) F = m \cdot g = 100 \cdot 9.81 \frac{\text{m}}{\text{s}^2} \approx 1000 \text{ N} = 1 \text{ kN}$
 $2) \sum F_{xk} = 0$
 $\sum F_{yA} = 0: F_{yA} - F = 0$
 $\Rightarrow F_{yA} = F = 1 \text{ kN}$
 $\sum M_A = 0: M_A = F \cdot x = 1 \text{ kN} \cdot 100 \text{ mm}$
 $\Rightarrow M_b = 100 \text{ kNm}$
 $3) d_{b, \text{max}} = \frac{M_b}{F_{\text{ax}} \cdot \frac{D}{2}} = \frac{M_b}{W_{\text{ax}}}$
 $W_{\text{ax}} = F_{\text{ax}} = \frac{\pi}{64} \cdot D^4$
 $\Rightarrow d_{b, \text{max}} = \frac{32 \cdot M_b}{\pi D^3} = \frac{M_b}{W_{\text{ax}}}$ where it is: $W_{\text{ax}} = \frac{\pi D^3}{32}$
 $\Rightarrow d_{b, \text{max}} = \frac{100 \text{ kNm}}{100 \text{ mm}^3} = \frac{1 \text{ kN}}{\text{mm}^2} = 1000 \text{ MPa}$
 $\Rightarrow \text{Search for materials with strength} \geq 1000 \text{ MPa}$

Given:

- Cyclist's weight $m=100 \text{ kg}$
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- Vertical distance between saddle and seat clamp $y=200 \text{ mm}$
- Diameter of the seat post $D=10 \text{ mm}$

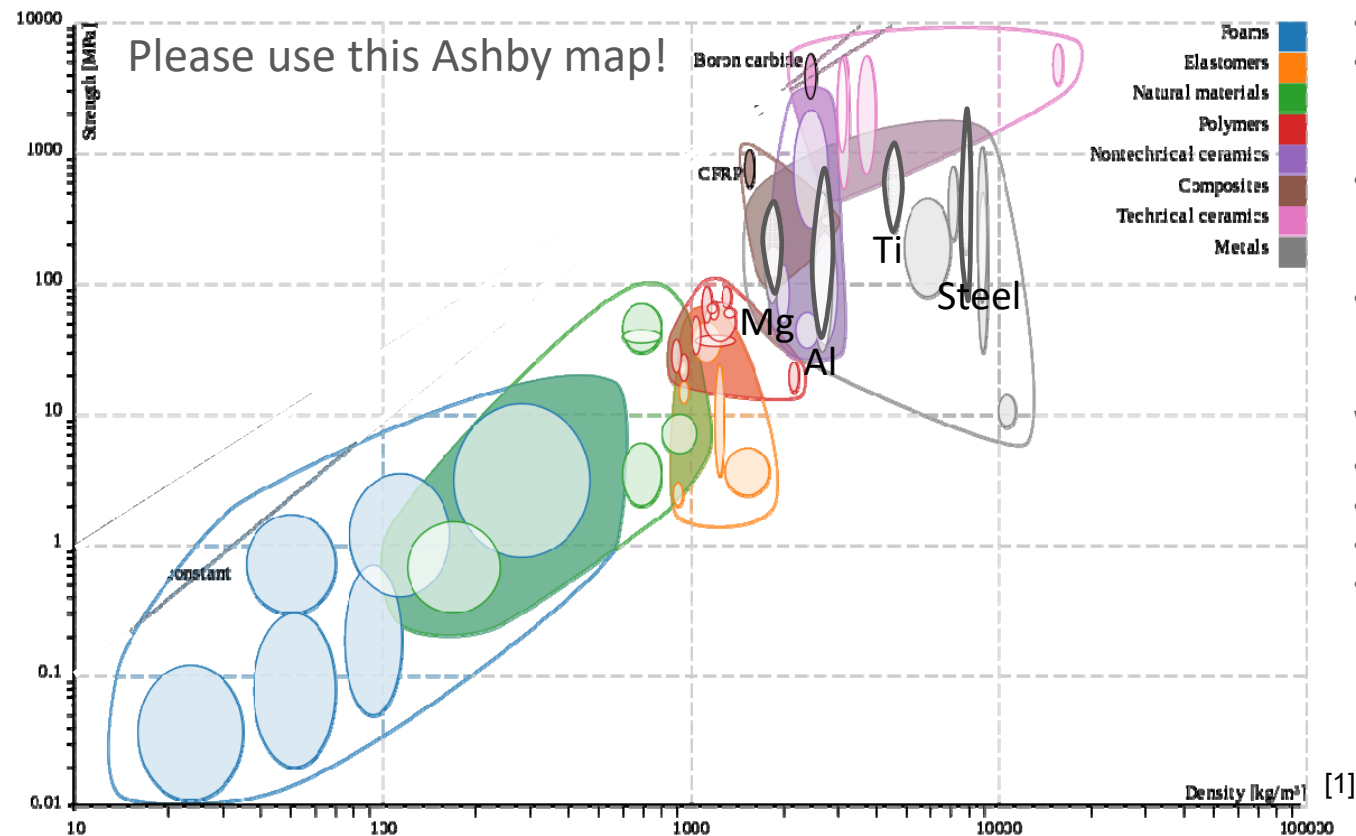
Wanted:

- Location of the highest load
- Type of local load
- Level of local load
- The seat post's right material choice (i.e. the lightest considered metal)

Design and dimensioning

How can we find the seat post's right* material?

*) means light and strong



Given:

- Cyclist's weight $m=100$ kg
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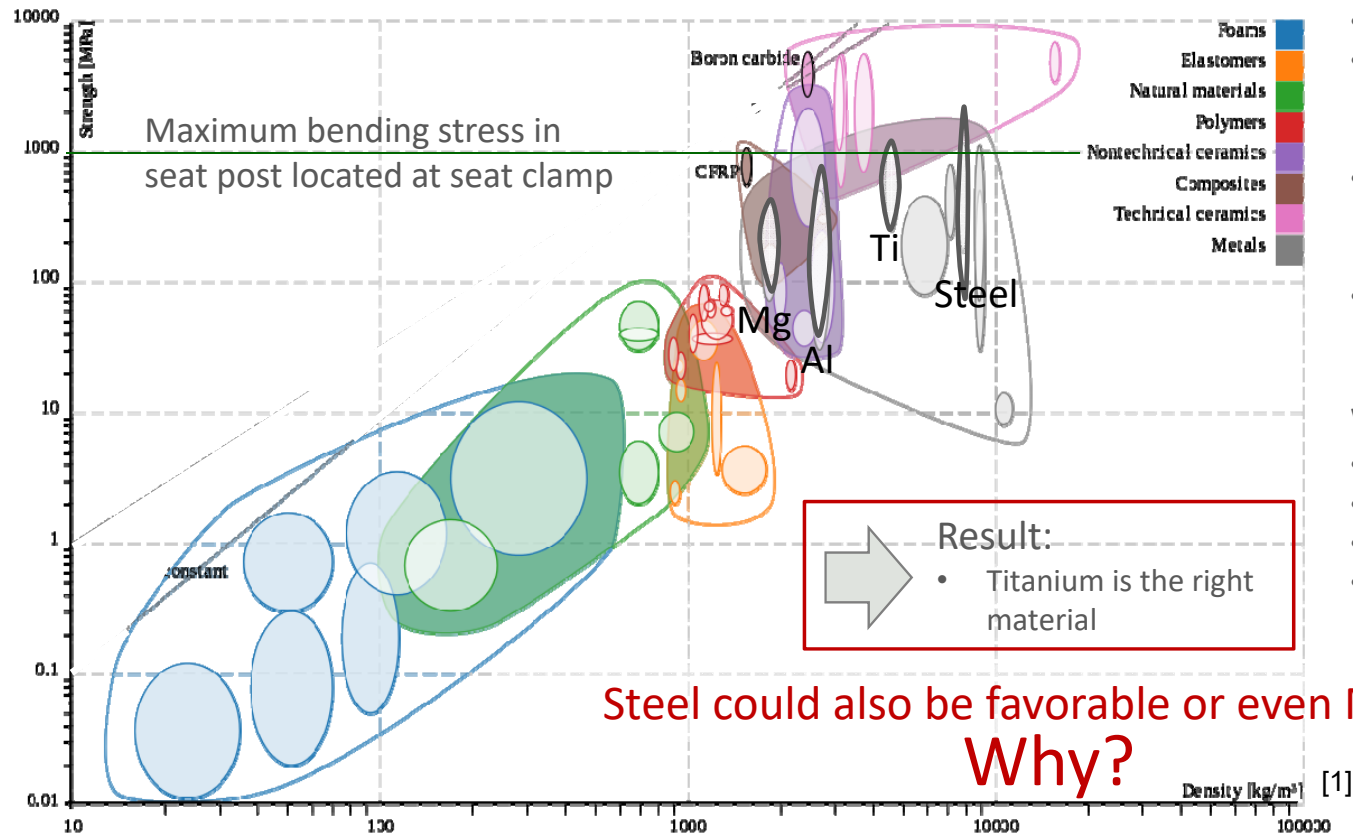
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1.2 Material oriented approaches

Design and dimensioning

How can we find the seat post's right* material?

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Given:

- Cyclist's weight $m=100$ kg
- Horizontal distance between saddle and seat clamp $x=100$ mm
- Vertical distance between saddle and seat clamp $y=200$ mm
- Diameter of the seat post $D=10$ mm

Wanted:

- Location of the highest load
- Type of local load
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1.2 Material oriented approaches

Design and dimensioning

How can we find the seat post's right* material?

*) means light and strong

	Magnesium	Aluminum	Titanium	Steel	
Cyclist mass m	100	100	100	100	kg
Lever arm length x	100	100	100	100	mm
Cyclist force F	1000	1000	1000	1000	N
Bending moment Mb	100000	100000	100000	100000	Nmm
Seatpost diameter D	16,3	12,9	10	7,6	mm
Seatpost Length L	225	225	225	225	mm
Resistance moment W	422,8	211,2	98,2	42,6	mm ³
Bending stress σ_b max	237	473	1019	2347	MPa
Seatpost cross section A	207,9	130,9	78,5	45,0	mm ²
Density ρ	1700,0	2700,0	4500,0	7850,0	kg/m ³
Seatpost mass $m = \rho \cdot A \cdot L$	0,080	0,080	0,080	0,080	kg

Given:

- Cyclist's weight $m=100$ kg
- Horizontal distance between saddle and seat clamp $x=100$ mm
- Vertical distance between saddle and seat clamp $y=200$ mm

Use as degree of freedom • Diameter of the seat post $D=10$ mm

Wanted:

- Location of the highest load
- Type of local load
- Level of local load
- The seat post's right material choice (i.e. the lightest considered metal)



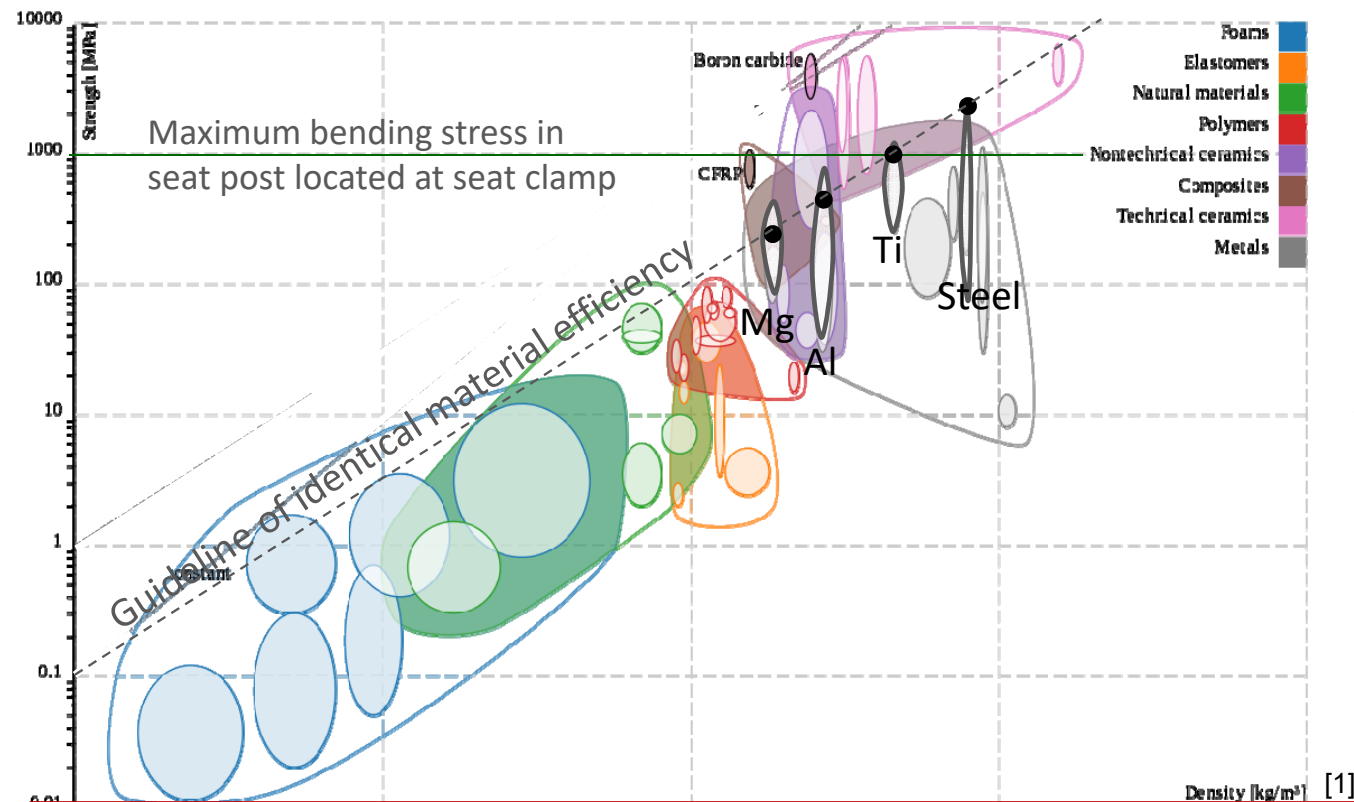
Extend the range of materials by exploiting geometric degrees of freedom

1.2 Material oriented approaches

Design and dimensioning

How can we find the seat post's right* material?

*) means light and strong



Given:

- Cyclist's weight $m=100$ kg
- Horizontal distance between saddle and seat clamp $x=100$ mm
- Vertical distance between saddle and seat clamp $y=200$ mm
- Degree of freedom:
Diameter of the seat post

Wanted:

- Location of the highest load
- Type of local load
- Level of local load
- The seat post's right material choice (i.e. the lightest considered metal)

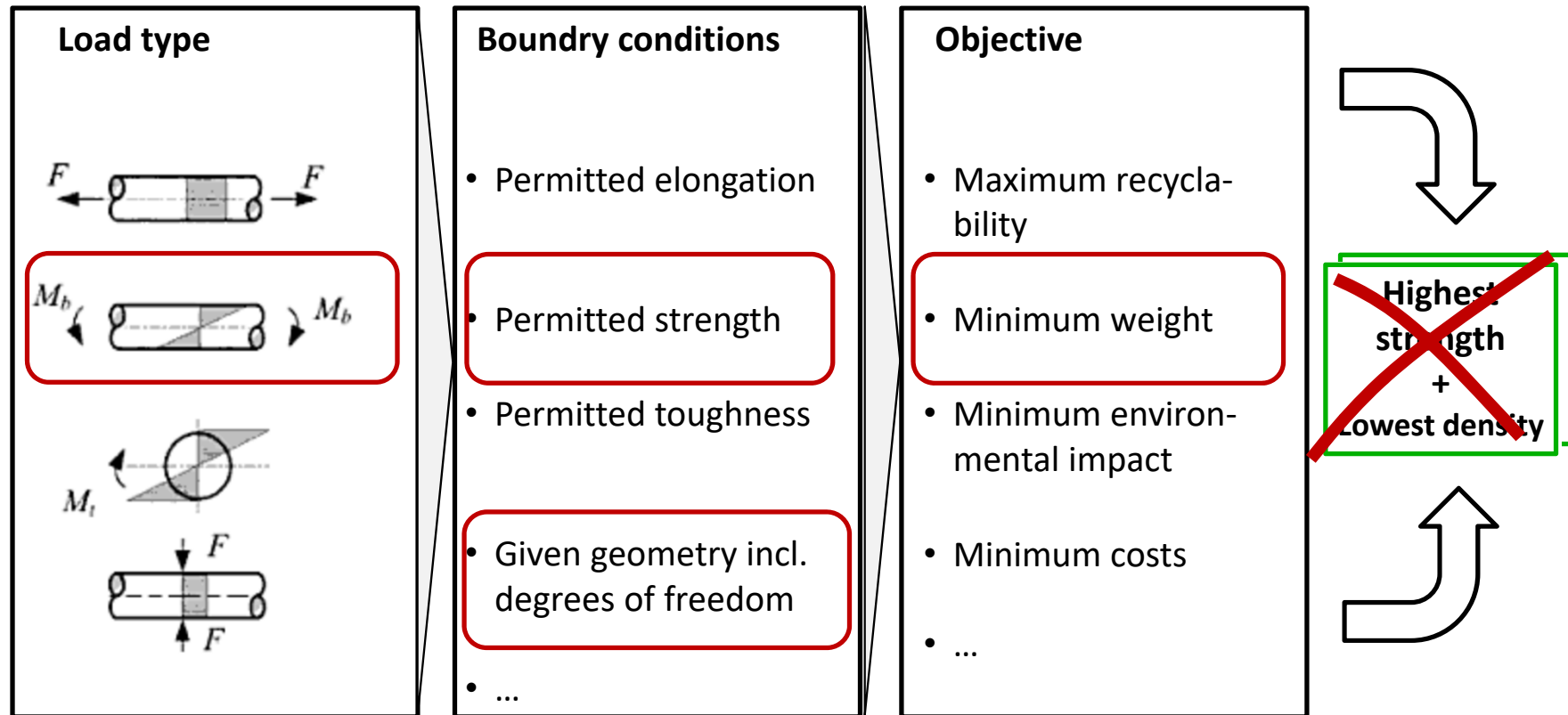


This brings us to the approach of **density specific material characteristics**

1.2 Material oriented approaches

Design and dimensioning

Design of a statically loaded, strong and light bending beam

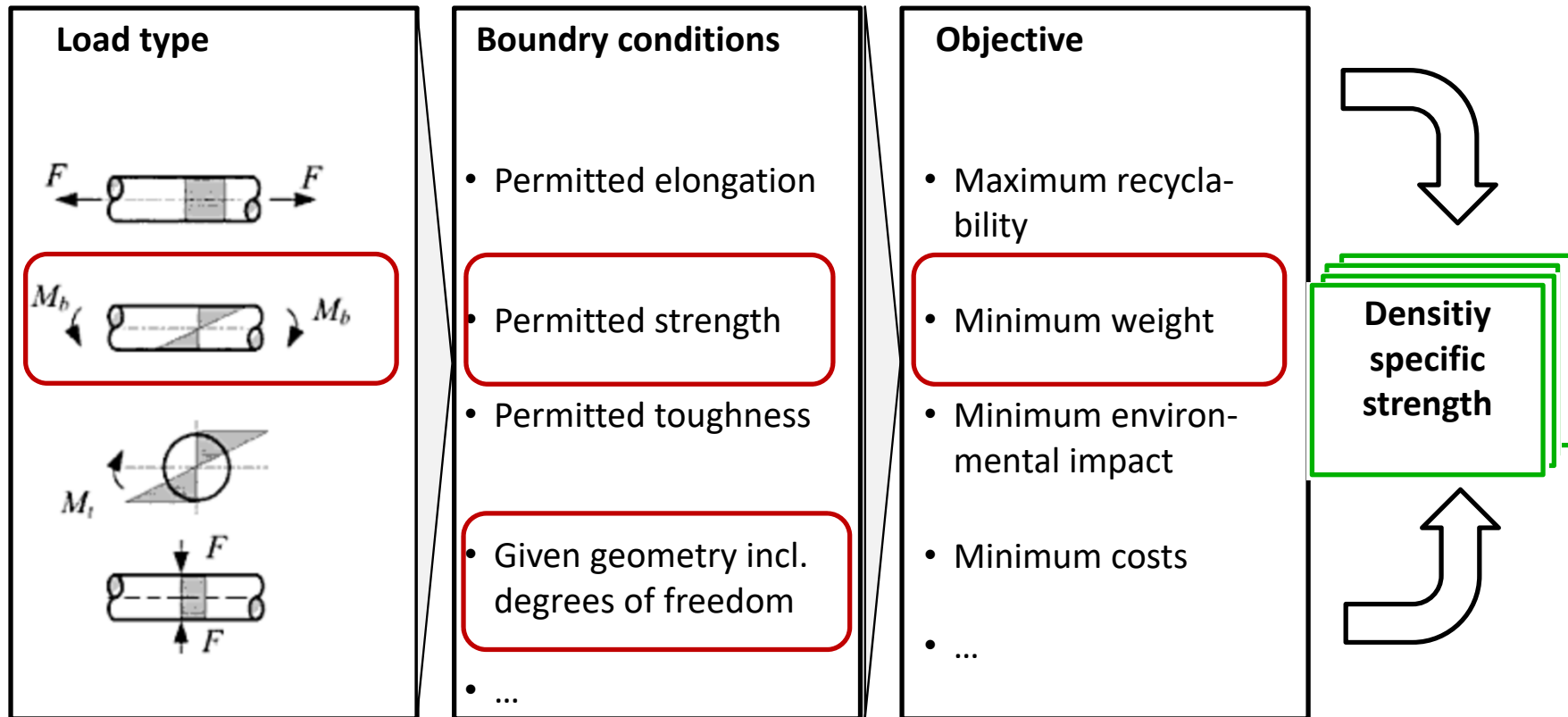


Wrong approach! Why?

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Design and dimensioning with density specific material characteristics

Design of a statically loaded, strong and light bending beam

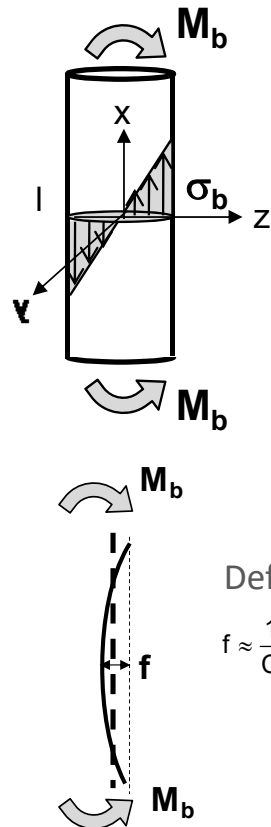


For an integrative approach density specific material characteristics are needed

1.2 Material oriented approaches

Design and dimensioning with density specific material characteristics

Example: Design of a statically loaded, strong and light bending beam



Deflection

$$f \approx \frac{1}{C} \cdot \frac{M_b \cdot l^2}{E \cdot J_{ax}}$$

Boundary conditions: Degrees of freedom

- Bending moment M_b
- Length l
- Cross section A

Derivation of the density specific material characteristics (MC):

$$\rightarrow \sigma_{b,max} = \sigma = \frac{M_b}{J_{ax}} \cdot \frac{D}{2} \quad (\text{Bending strength})$$

$$\text{with: } J_{ax} = \frac{A^2}{4 \cdot \pi} = \frac{\pi}{64} \cdot D^4$$

$$\text{and: } \underline{m = \rho \cdot V = \rho \cdot \frac{\pi}{4} D^2 \cdot l \rightarrow \text{MIN}} \Rightarrow D = \sqrt{\frac{4 \cdot m}{\pi \cdot \rho \cdot l}}$$

$$\Leftrightarrow \sigma^2 = \frac{16 \cdot \pi \cdot M_b^2 \cdot \rho^3 \cdot l^3}{m^3}$$

$$\Leftrightarrow \frac{\sigma^2}{\rho^3} = \frac{16 \cdot \pi \cdot M_b^2 \cdot l^3}{m^3} \quad \Leftrightarrow \frac{\sqrt[3]{\sigma^2}}{\rho} = \frac{2 \cdot l}{m} \cdot \sqrt[3]{2 \cdot \pi \cdot M_b^2}$$

$$\boxed{\Leftrightarrow MC = \frac{\sqrt[3]{\sigma^2}}{\rho} \rightarrow \text{MAX}}$$

1.2 Material oriented approaches

Design and dimensioning with density specific material characteristics

How can we find the seat post's right* material?

*) means light and strong

	Magnesium	Aluminum	Titanium	Steel	
Cyclist mass m	100	100	100	100	kg
Lever arm length x	100	100	100	100	mm
Cyclist force F	1000	1000	1000	1000	N
Bending moment Mb	100000	100000	100000	100000	Nmm
Seatpost diameter D	16,3	12,9	10	7,6	mm
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Seatpost mass $m = \rho \cdot A \cdot L$	0,080	0,080	0,080	0,080	kg

Given:

- Cyclist's weight $m=100$ kg
- Horizontal distance between saddle and seat clamp $x=100$ mm
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Use as degree of freedom • Diameter of the seat post $D=10$ mm

Wanted:

- Location of the highest load
- Type of local load
- Level of local load
- The seat post's right material choice (i.e. the lightest considered metal)



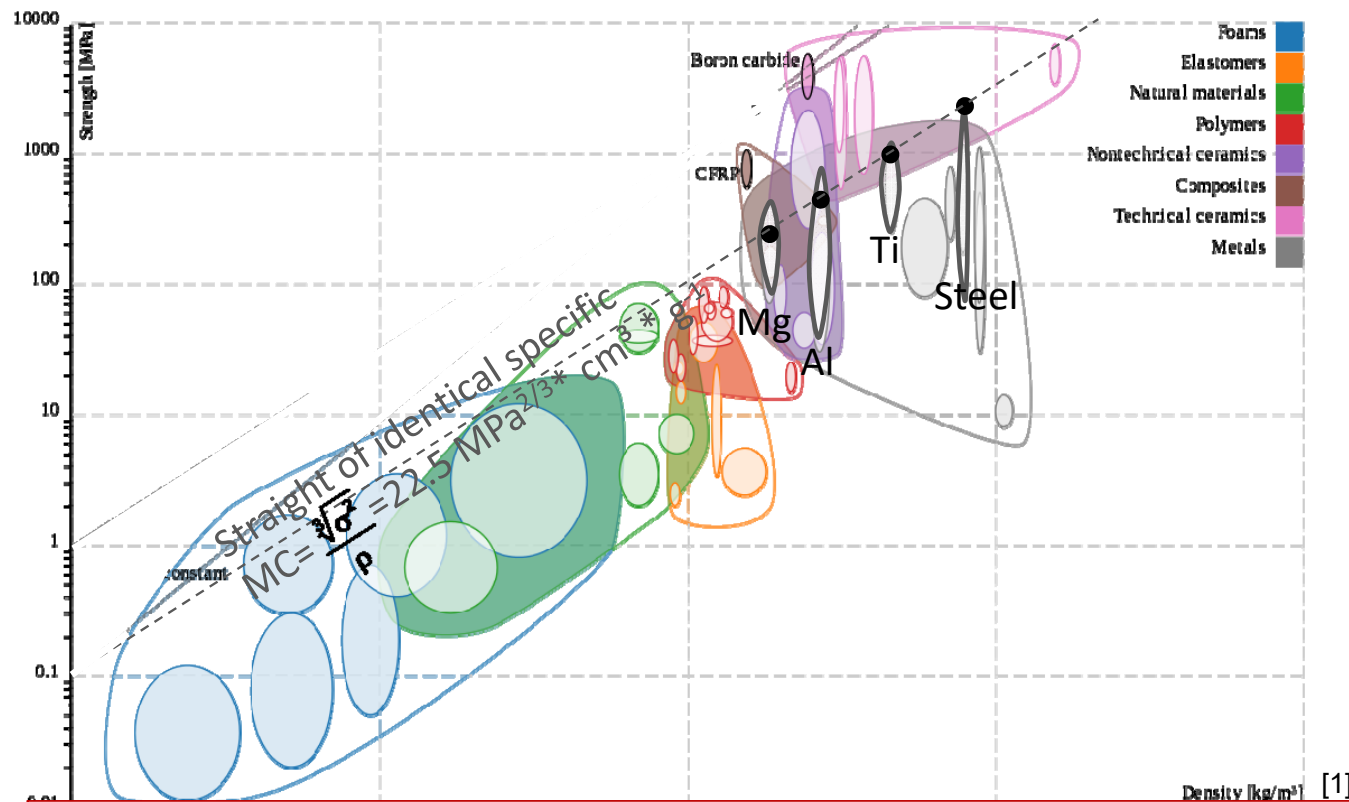
The same density specific MC means the same material efficiency

1.2 Material oriented approaches

Design and dimensioning with density specific material characteristics

How can we find the seat post's right* material?

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Given:

- Cyclist's weight $m=100 \text{ kg}$
- Horizontal distance between saddle and seat clamp $x=100 \text{ mm}$
- Vertical distance between saddle and seat clamp $y=200 \text{ mm}$
- Degree of freedom: Diameter of the seat post

Wanted:

- Location of the highest load
- Type of local load
- Level of local load
- The seat post's right material choice (i.e. the lightest considered metal)

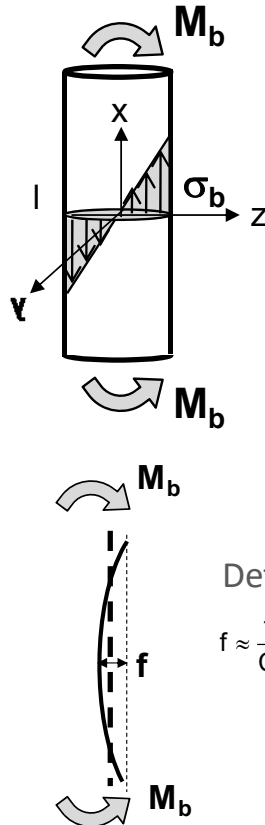


All Materials on the line provide the same specific MC of $22.5 \text{ MPa}^{2/3} \cdot \text{cm}^3 \cdot \text{g}^{-1}$

1.2 Material oriented approaches

Design and dimensioning with density specific material characteristics

Example: Design of a statically loaded, stiff and light bending beam



Deflection

$$f \approx \frac{1}{C} \cdot \frac{M_b \cdot l^2}{E \cdot J_{ax}}$$

Boundary conditions: Degrees of freedom

- Bending moment M_b
- Length l
- Deflection f
- Cross section A

Derivation of the density specific material characteristics (MC):

$$\rightarrow E \cdot J_{ax} \approx \frac{M_b \cdot l^2}{C \cdot f} \quad (\text{Bending stiffness})$$

$$\text{mit: } J_{ax} = \frac{A^2}{4 \cdot \pi} = \frac{\pi}{64} \cdot D^4$$

$$\text{und: } \underline{m = \rho \cdot V = \rho \cdot A \cdot l \rightarrow \text{MIN}} \Rightarrow A = \frac{m}{\rho \cdot l}$$

$$\Leftrightarrow \frac{E \cdot m^2}{4 \cdot \pi \cdot \rho^2 \cdot l^2} = \frac{M_b \cdot l^2}{C \cdot f}$$

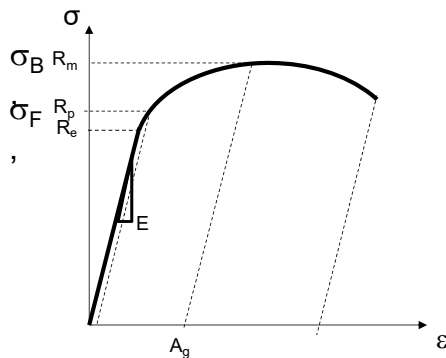
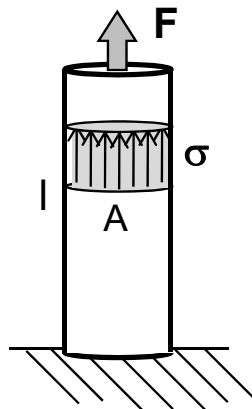
$$\Leftrightarrow \frac{E}{\rho^2} = \frac{M_b \cdot 4 \cdot \pi \cdot l^4}{m^2 \cdot C \cdot f} \Leftrightarrow \frac{\sqrt{E}}{\rho} = \frac{1}{m} \cdot \sqrt{\frac{M_b \cdot 4 \cdot \pi \cdot l^4}{C \cdot f}}$$

$$\boxed{\Leftrightarrow MC = \frac{\sqrt{E}}{\rho} \rightarrow \text{MAX}}$$

1.2 Material oriented approaches

Design and dimensioning with density specific material characteristics

Example: Design of a statically loaded, strong and light tension bar



Boundary conditions: Degrees of freedom

- Permissible Force F
- Cross section A
- Length l

Derivation of the density specific material characteristics (MC):

$$\rightarrow \sigma_{zul} = \frac{F}{A} \quad (\text{Tensile strength})$$

$$\text{with: } m = \rho \cdot V = \rho \cdot A \cdot l \rightarrow \text{MIN} \Rightarrow A = \frac{m}{\rho \cdot l}$$

$$\Leftrightarrow \sigma_{zul} = \frac{F \cdot \rho \cdot l}{m}$$

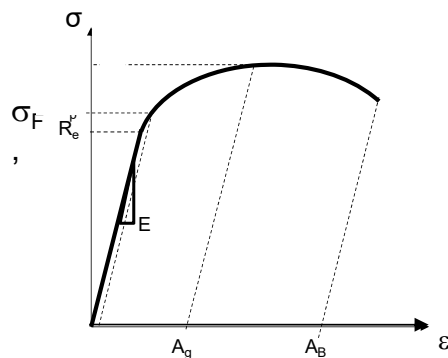
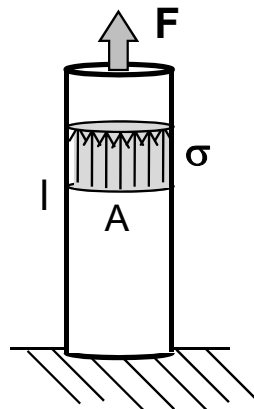
$$\Leftrightarrow \frac{\sigma_{zul}}{\rho} = \frac{F}{m} \cdot l$$

$$\Leftrightarrow \text{MC} = \frac{\sigma}{\rho} \rightarrow \text{MAX} \quad (\text{whereas: } \sigma = \sigma_F, \sigma_B, R_p, R_e, R_m \dots)$$

1.2 Material oriented approaches

Design and dimensioning with density specific material characteristics

Example: Design of a statically loaded, stiff and light tension bar



Boundary conditions: Degrees of freedom

- Permissible elongation ε
- Permissible Force F
- Length l
- Cross section A

Derivation of the density specific material characteristics (MC):

$$\rightarrow E \cdot A = \frac{F}{\varepsilon_{zul}} \quad (\text{Tensile stiffness})$$

$$\text{mit: } m = \rho \cdot V = \rho \cdot A \cdot l \rightarrow \text{MIN} \Rightarrow A = \frac{m}{\rho \cdot l}$$

$$\Leftrightarrow \varepsilon_{zul} = \frac{F \cdot \rho \cdot l}{E \cdot m}$$

$$\Leftrightarrow \frac{E}{\rho} = \frac{F}{m \cdot \varepsilon_{zul}} \cdot l$$

$$\Leftrightarrow \text{MC} = \frac{E}{\rho} \rightarrow \text{MAX}$$

1.2 Material oriented approaches

Design and dimensioning with density specific material characteristics

Overview (selection)

Load type/body	Boundary conditions	Degree of freedom	MCs for dimensioning acc. to		
			Stiffness	Strength	Toughness
Tension/ compression rod	Force, length	Cross-sectional area	$\frac{E}{\rho}$	$\frac{\sigma}{\rho}$	$\frac{K_{Ic}}{\rho}$
Shaft, torsionally stressed	Moment, length	Cross-sectional area	$\frac{\sqrt{G}}{\rho}$	$\frac{\sqrt[3]{\sigma^2}}{\rho}$	$\frac{\sqrt[3]{K_{Ic}^2}}{\rho}$
	Moment, length, outside diameter	Wall thickness	$\frac{G}{\rho}$	$\frac{\sigma}{\rho}$	$\frac{K_{Ic}}{\rho}$
	Moment, length, wall thickness	Outer diameter	$\frac{\sqrt[3]{G}}{\rho}$	$\frac{\sqrt{\sigma}}{\rho}$	$\frac{\sqrt{K_{Ic}}}{\rho}$
Bending beam	Force or moment, (deflection), length	Cross-sectional area	$\frac{\sqrt{E}}{\rho}$	$\frac{\sqrt[3]{\sigma^2}}{\rho}$	$\frac{\sqrt[3]{K_{Ic}^2}}{\rho}$
	Force or moment, (deflection), length, height	Width	$\frac{E}{\rho}$	$\frac{\sigma}{\rho}$	$\frac{K_{Ic}}{\rho}$
	Force or moment, (deflection), length, width	Hights	$\frac{\sqrt[3]{E}}{\rho}$	$\frac{\sqrt{\sigma}}{\rho}$	$\frac{\sqrt{K_{Ic}}}{\rho}$
Buckling bar	Force, length	Cross-sectional area	$\frac{\sqrt{E}}{\rho}$	$\frac{\sigma}{\rho}$	$\frac{K_{Ic}}{\rho}$

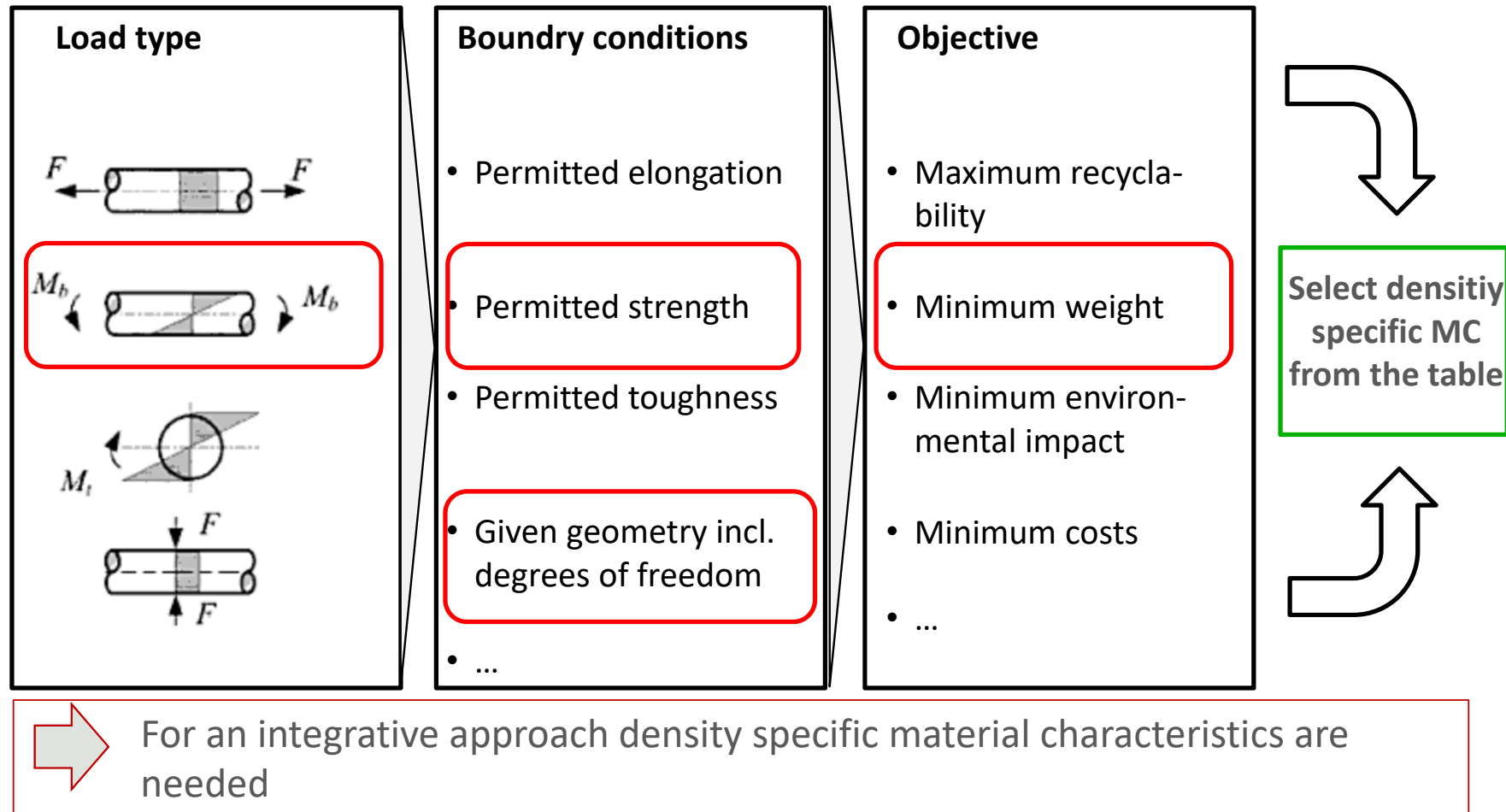
σ : Strength (ultimate and yield strength respectively)

(acc. to M.F. Ashby)

1.2 Material oriented approaches

Material selection

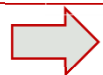
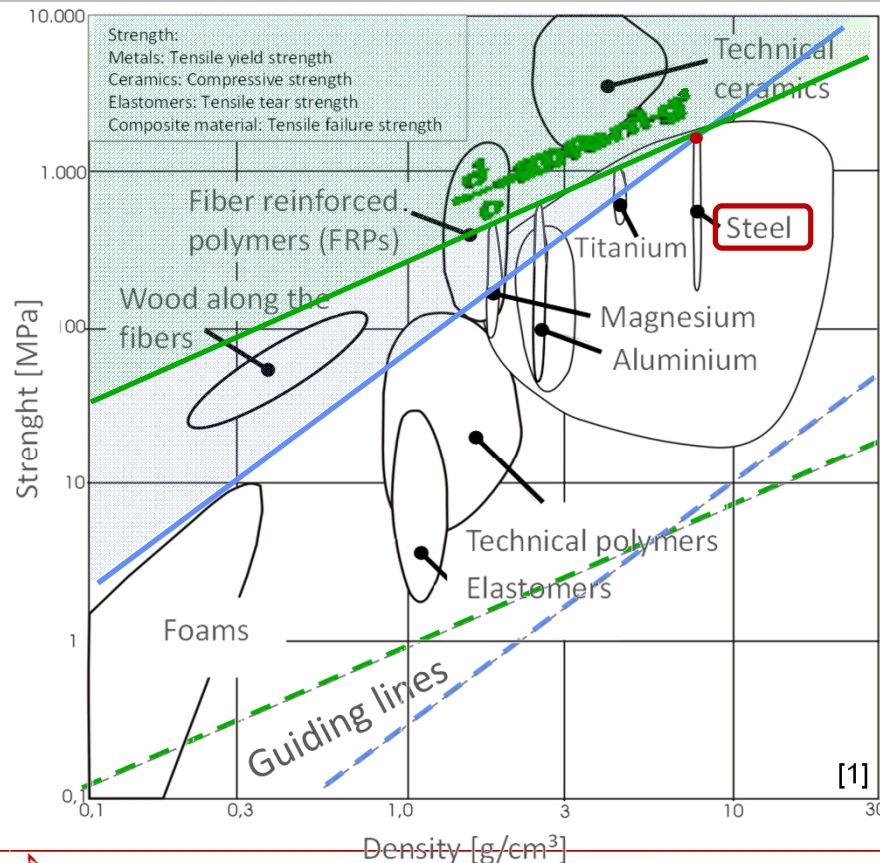
Pre-select load type, boundary conditions and objective for your component



1.2 Material oriented approaches

Material selection

How to find the right material with Ashby maps



All Materials above the line provide a higher, below a lower lightweight potential

- Transformation of density specific strength into a straight equation:

$$\rightarrow MC = \frac{\sigma^n}{\rho} \rightarrow \text{MAX}$$

$$\Leftrightarrow \log \sigma^n = \log \rho + \log MC$$

$$\Leftrightarrow \log \sigma = \frac{1}{n} \cdot \log \rho + \frac{1}{n} \cdot \log MC$$

(Base equation: $y = m \cdot x + b$)

- Tensile/ compression loading

$$\rightarrow n = 1 \Leftrightarrow \frac{1}{n} = 1$$

- Bending loading (bending beams with circular cross sections)

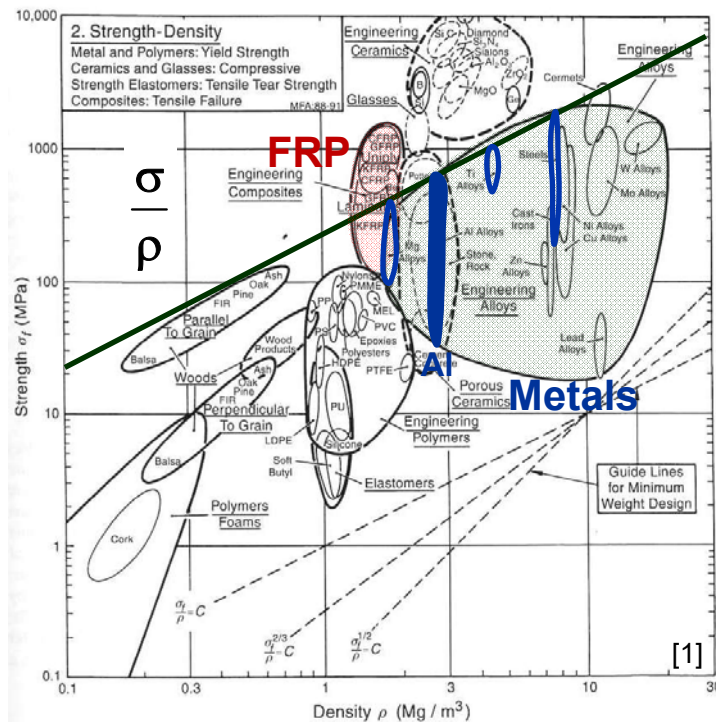
$$\rightarrow n = \frac{2}{3} \Leftrightarrow \frac{1}{n} = \frac{3}{2}$$

1.2 Material oriented approaches

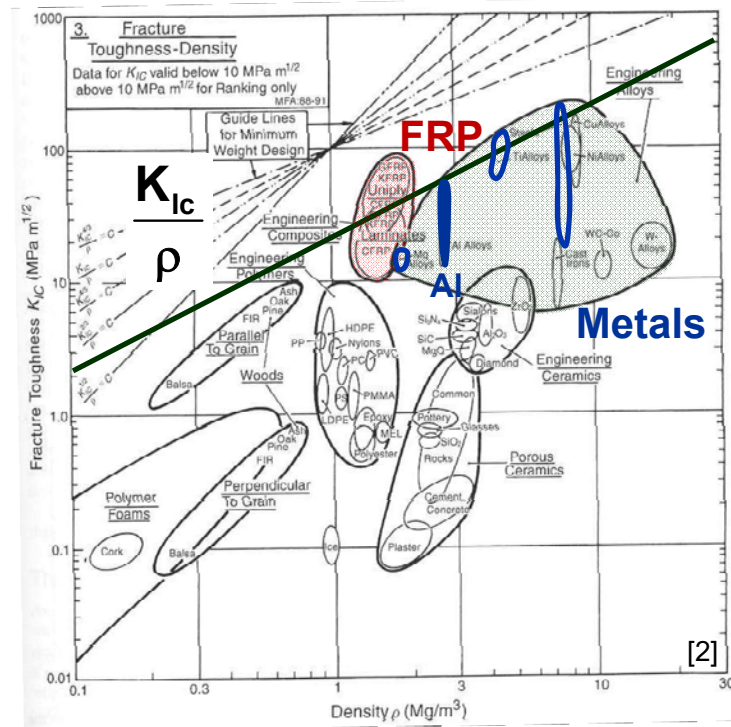
Material selection

How to find the right material with Ashby maps

Strong and light tensile/compression bar*



Tough and light tensile/compression bar*



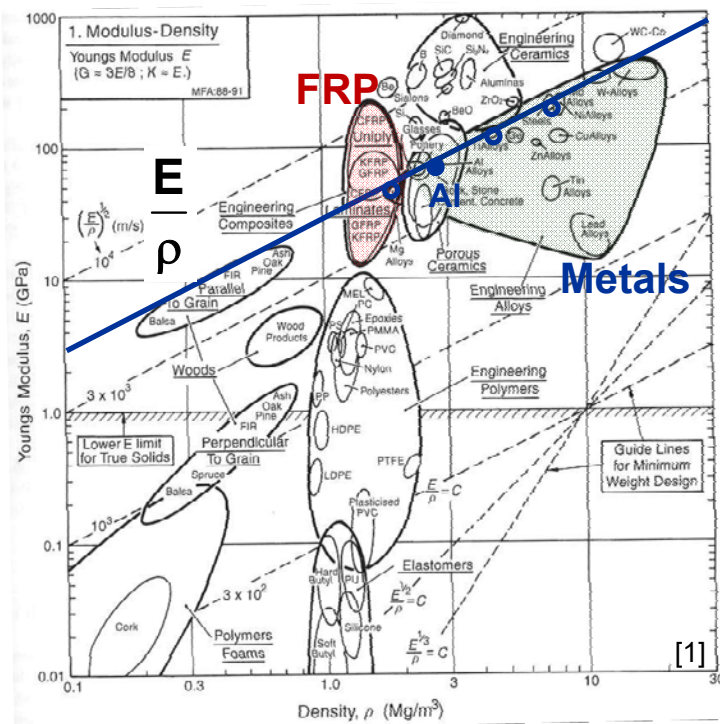
*) Reference: Aluminium

1.2 Material oriented approaches

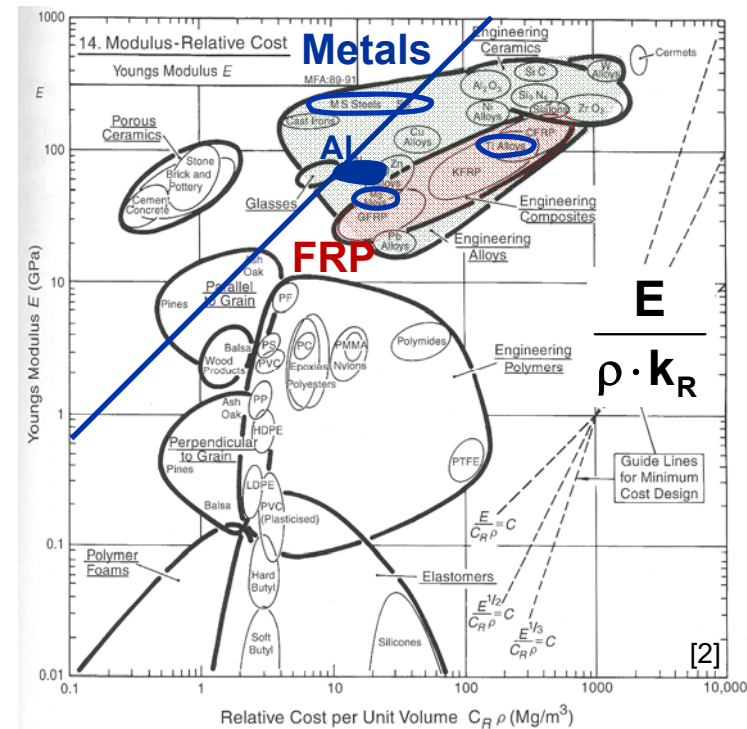
Material selection

How to find the right material with Ashby maps

Stiff and light tensile/compression bar*



Stiff, light and cost-effective tensile/compression bar*

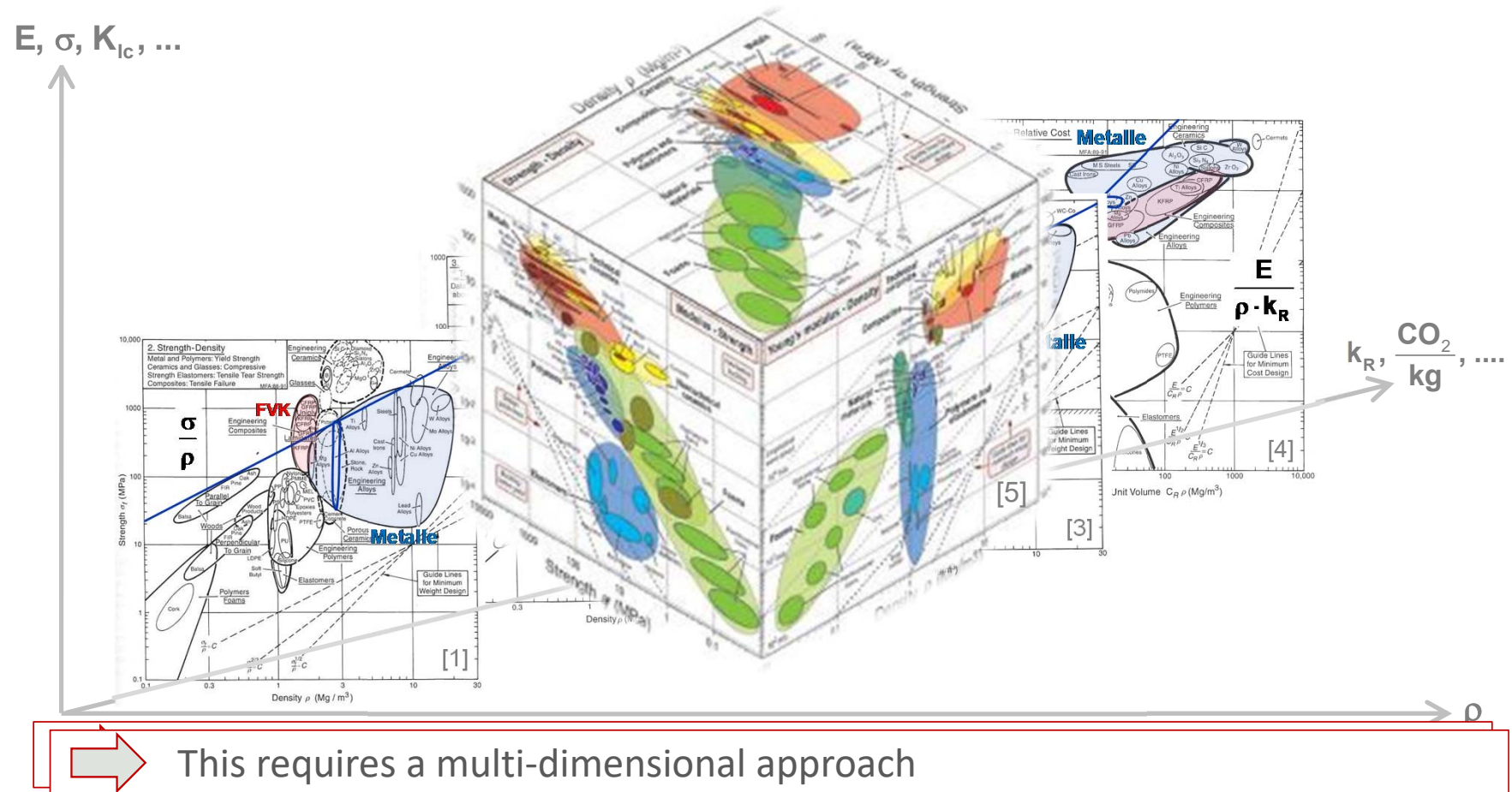


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1.2 Material oriented approaches

Material selection

How to find the right material with Ashby maps



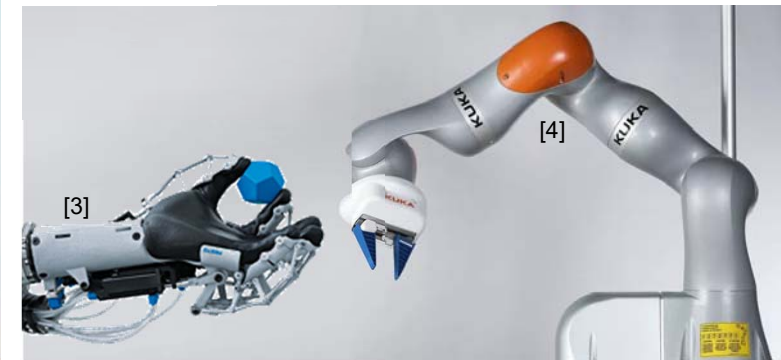
1.2 Material oriented approaches

Material oriented approaches

Summary

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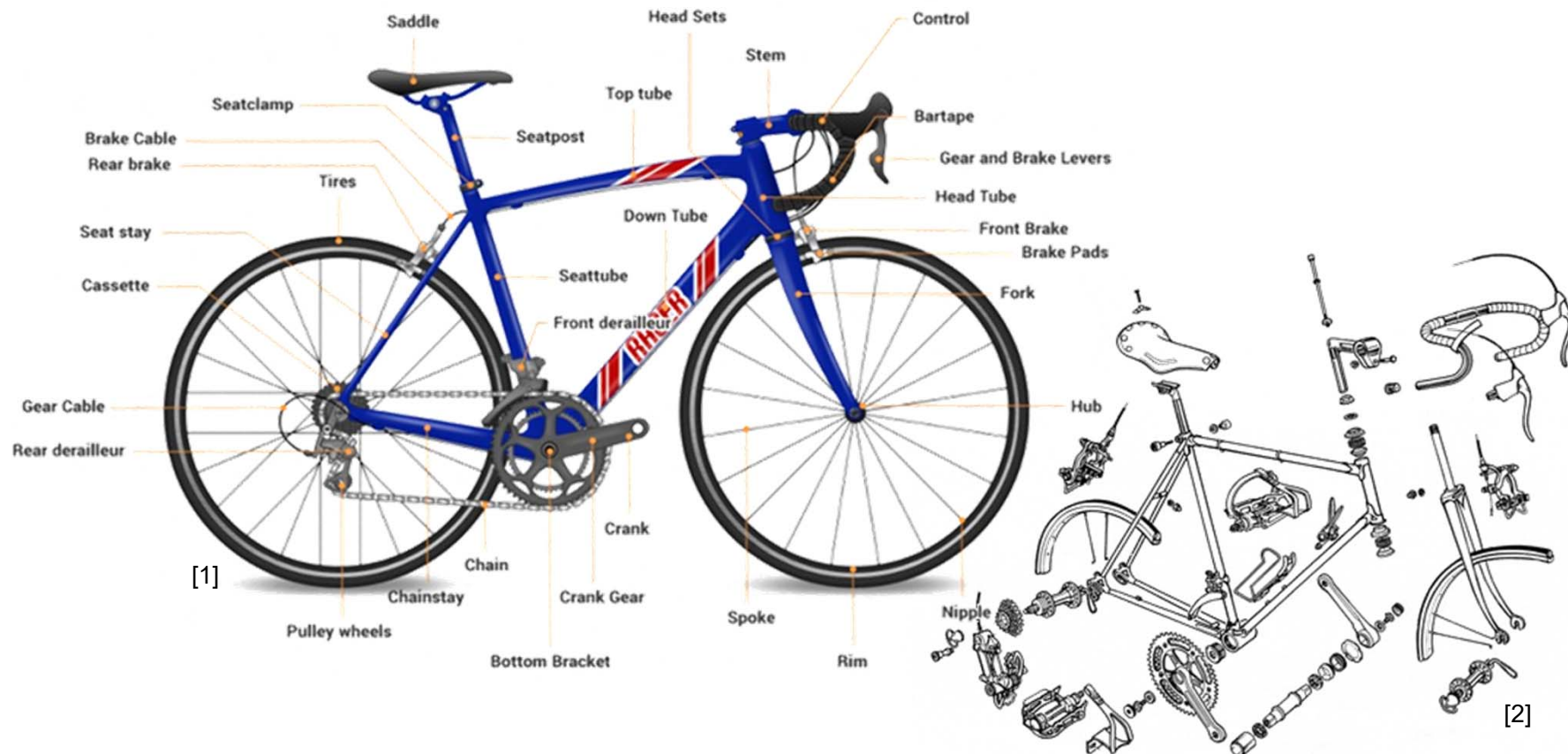
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1.2 Material oriented approaches

Case study

How can we find the right* material for the frame?



*) means light and stiff

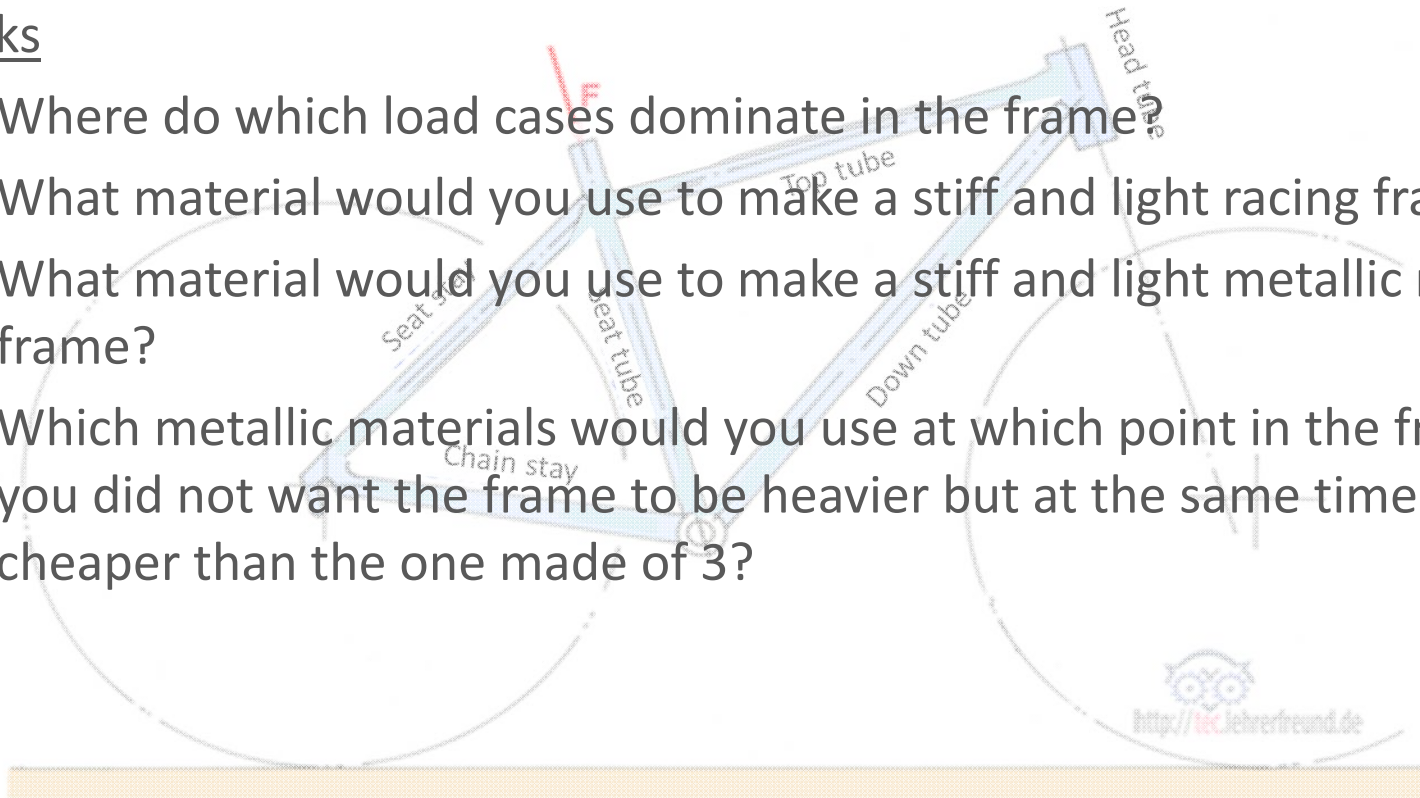
1.2 Material oriented approaches

Case study

How can we find the right* material for the frame?

Tasks

1. Where do which load cases dominate in the frame?
2. What material would you use to make a stiff and light racing frame?
3. What material would you use to make a stiff and light metallic racing frame?
4. Which metallic materials would you use at which point in the frame if you did not want the frame to be heavier but at the same time cheaper than the one made of 3?



<http://www.lehrerfreund.de/technik/1s/kraefte-am-fahrrad1/4000>

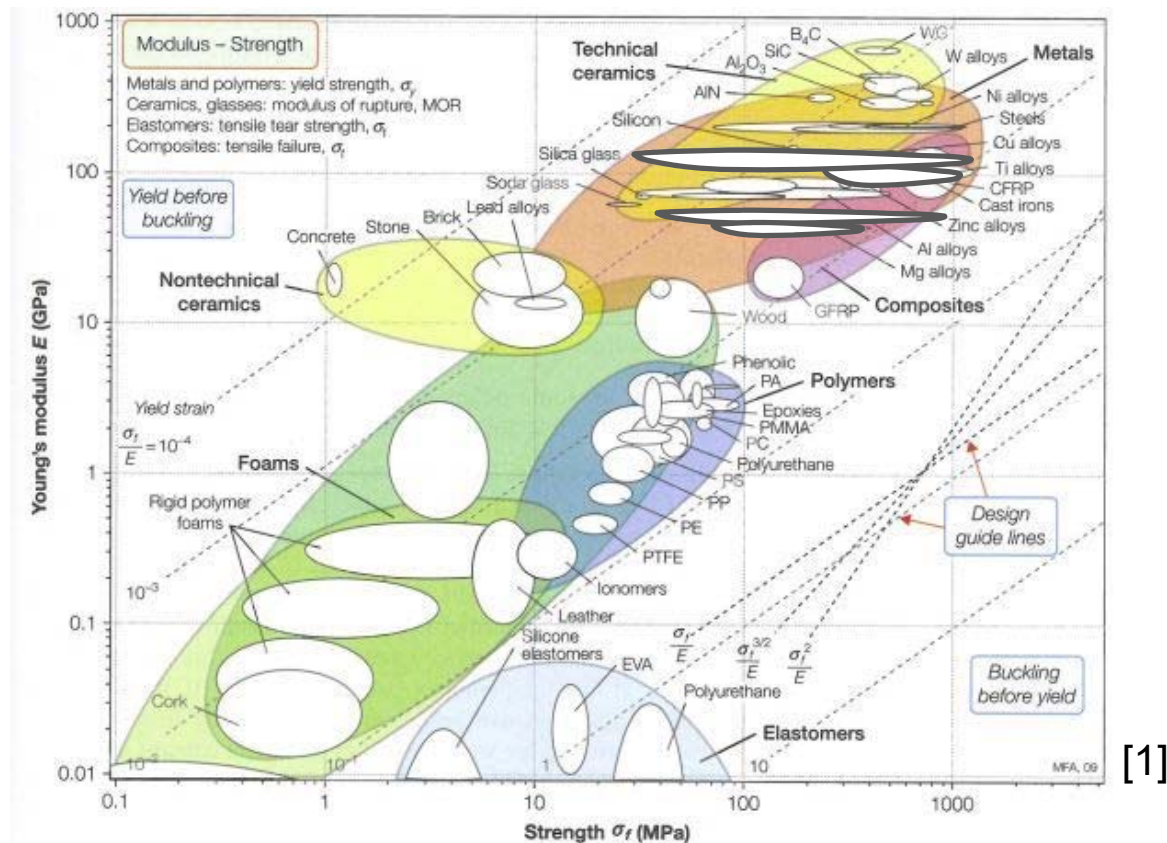
1.2 Material oriented approaches

Lightweight Materials - Their Properties, Technologies and Advanced Applicability

Content

Series No.	Volume of Lectures	Title/Content
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	1	1.3 Metallic Materials Mechanisms of Strength Increase and their Industrial Use
2	3	2.1 Advanced Alloys (part 1): Steels Multi-Phase Steels and TRIP/TWIP for Automotive Applications
3	3	2.2 Advanced Alloys (part 2): Aluminium Alloys Age-hardenable Alloys for Automotive and Aerospace Applications
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➡ The large potential for strengthening is indicated by the elongated ellipses

1.2 Material oriented approaches

Lightweight Materials Their Properties, Technologies and Advanced Applicability

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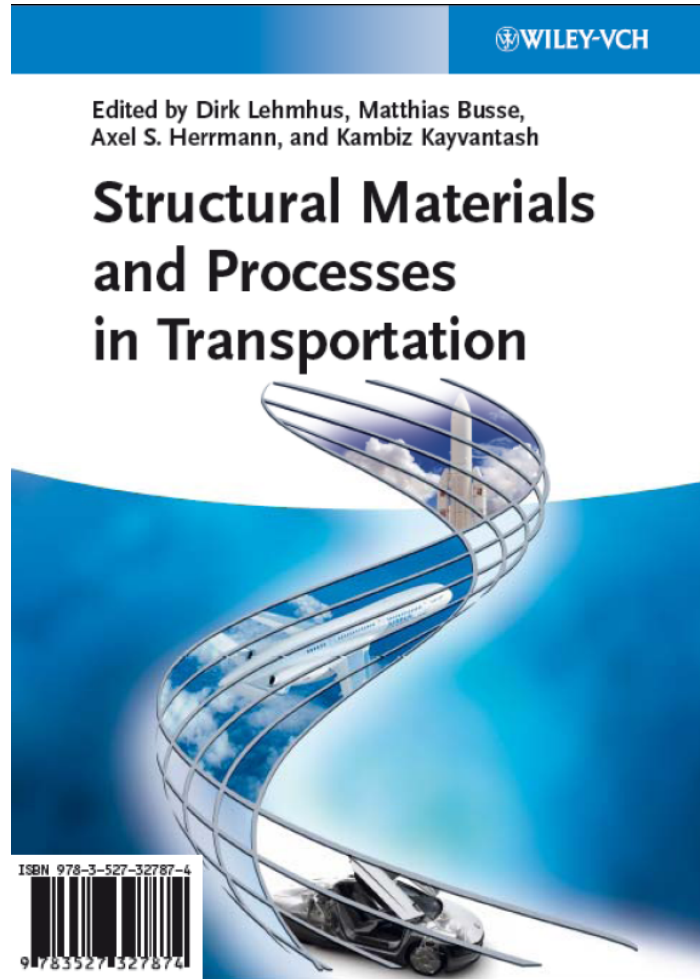
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Further reading



<http://onlinelibrary.wiley.com/book/10.1002/9783527649846>

Part I Metals *Axel von Hehl*

- 1 **Steel and Iron based alloys**
Udo Prah, A. Ramazani, and B. Berm
- 2 **Aluminum and Aluminum Alloys**
Axel von Hehl and Peter Krug
- 3 **Magnesium and Magnesium Alloys**
Wim. H. Sillekens and Norbert. Hort
- 4 **Titanium and Titanium Alloys**
Lothar Wagner and Manfred Wollmann

Part II Polymers

- 5 **Thermoplastics**
Aravind Dasari
- 6 **Thermosets**
Sergio Henrique Pezzin, Luiz Antonio, Sandro Campos Amico, and Luiz Cláudio Pardini
- 7 **Elastomers**
Krzysztof Pielichowski and James Njuguna

Part III Composites

- 8 **Polymer Matrix Composites**
Axel. S. Herrmann, A. Stieglitz, C. Brauner, C. Peters, and P. Schiebel
- 9 **Metal Matrix Composites**
Maider Garcia-de Cortazar, Pedro Egizabal, Jorge Barcena, and Yann Le Le Petitcorps
- 10 **Polymer Nanocomposites**
James Njuguna and Krzysztof Pielichowski

Part IV Cellular Materials

- 11 **Polymer Foams**
Eusebio Solorzano and Miguel. A. Rodriguez-Perez
- 12 **Metal Foams**
Joachim Baumeister and Jörg Weise

Part V Modelling and Simulation

- 13 **Advanced Simulation and Optimization Techniques**
Jörg Hohe
- 14 **An Artificial-Intelligence-Based Approach for Generalized Material Modeling**
Kambiz Kayvantash
- 15 **Ab Initio Guided Design of Materials**
M. Friak, D. Raabe, and J. Neugebauer

Part VI Higher Level Trends

- 16 **Hybrid Design Approaches**
Daniele Bassan
- 17 **Sensorial Materials**
Dirk Lehmhus and Stefan Bosse
- 18 **Additive Manufacturing Approaches**
Juan Isaza and Claus Aumund-Koop

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1.2 Material oriented approaches

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